

# HARSH SHARMA

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## INTERESTS

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Computer Vision, Image Processing, Artificial Intelligence, Deep Learning, Machine Learning

## EDUCATION

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**M. Sc. in Computing Science with specialization in Multimedia** *Sept 2018-Present*  
UNIVERSITY OF ALBERTA, Edmonton, Canada

**B.E. (Hons.) Electrical and Electronics Engineering** *AUG 2011-JUL 2015*  
BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, Pilani, India  
CGPA: 7.19/10.00

## WORK EXPERIENCE

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**Software Developer, Seven Lakes Technologies, Bangalore, India** *OCT 2016-JULY 2018*  
*Core member of the Joyn-FDG<sup>TM</sup> app development team* *C#, Objective C, Java, JavaScript, Python*

- Implemented dynamic route generation algorithm - a priority based algorithm that helps the client prioritize the work and improve efficiency(Java)
- Helped stabilize the windows application by implementing features like auto update and intra-day readings (C#/.NET)
- Developed several key features for the windows and iOS applications and helped the company secure important deals (WPF/.NET/C#/Objective-C)
- Collaborated on the development of the new Joyn-FDG<sup>TM</sup> SaaS product (Node.js)
- Initiated the process of writing unit test cases for the Joyn<sup>TM</sup> Analytics platform (Python)

**Applications Engineer, Oracle India Pvt. Ltd., Bangalore, India** *JUN 2015-SEPT 2016*  
*Member of CPQ Cloud Development team* *Java, Oracle ADF*

- Worked on enhancing the existing functionality for the product
- Added support for titles, iconsets, accessibility and translations

## PROFESSIONAL TRAINING

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**Self-Driving Car Engineer** *DEC 2016-JAN 2018*  
NANODEGREE PROGRAM, UDACITY.COM *C++, Python - TensorFlow, Keras*

- Topics covered - Computer Vision, Deep Learning, Sensor Fusion, Localization, Control, Path Planning, Concentrations, and Systems

## INTERNSHIPS

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**Intern at Bharat Dynamics Limited, Hyderabad, India** *JUL-DEC 2014*  
*Real time detection and tracking of a moving colored object* *MATLAB, Python, OpenCV, VHDL*

- Extracted object of interest from the video frames using blob detection
- Used Kalman Filter to track and predict the path

**Summer Intern at Essar Power MP Ltd, Singrauli, India** *MAY-JUL 2013*

- Used HTML, CSS, JavaScript, PHP and MySQL to develop a database management system for the residents of the company township which replaced the existing manual process and brought down operational costs.
- Studied the working of an ESP, its various components and also the ESP Controller being used in the plant

- Studied and identified the various types of electrical faults and protection schemes implemented in the plant to prevent any type of damage

## PROJECTS

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- Classification of Parkinson's disease using DTI data** SEP-DEC 2018
  - Details will be added after project finishes
- Denoising images with a spatially varying gaussian noise** SEP-DEC 2018
  - Details will be added after project finishes
- Virtual Reality simulation for chest tube insertion process** SEP-DEC 2018
  - Details will be added after project finishes
- Programming a Real Self-Driving Car** DEC 2017
  - Capstone project for Udacity Self Driving Car Nano Degree
  - Developed using ROS
  - Implemented nodes for traffic light detection, waypoint following and control
  - Final project run on Udacity's Self Driving Car, Carla
- Semantic Segmentation** NOV 2017
  - Used a Fully Convolutional Network to label the pixels of a road in images.
- Path Planning** SEP 2017
  - Designed a path planner to create smooth, safe paths for the car to follow along a 3 lane highway with traffic
- Model Predictive Control** AUG 2017
  - Implemented a Model Predictive Control using a kinematic model to drive the car around the track.
  - Fitted the MPC by looking N points ahead spaced by dt seconds and fitting it to a third order polynomial.
- PID Controller** JULY 2017
  - Implement a PID controller in C++ to maneuver the vehicle around the track!
  - Utilized the cross track error (CTE) and the velocity (mph) from the simulator to compute the appropriate steering angle.
- Kidnapped Vehicle** JUNE 2017
  - Implemented a 2 dimensional particle filter in C++.
  - Used the parameters from the simulator to accurately localize the vehicle position and yaw
- Unscented Kalman Filter** MAY 2017
  - Utilized an Unscented Kalman Filter to estimate the state of a moving object of interest with noisy lidar and radar measurements
  - Code written in C++
- Extended Kalman Filter** APRIL 2017
  - Utilized a kalman filter to estimate the state of a moving object of interest with noisy lidar and radar measurements.
  - Code written in C++
- Vehicle Detection and Tracking** MARCH 2017
  - Identified vehicles in a video from a front-facing camera on a car.
  - Performed a Histogram of Oriented Gradients (HOG) feature extraction on a labeled training set of images and trained a Linear SVM classifier

- Implemented a sliding-window technique and used the trained classifier to search for vehicles in images.
- Tested the pipeline on a video stream
- Estimated a bounding box for the vehicles detected.

### **Advanced Lane Finding**

MARCH 2017

- Computed the camera calibration matrix and distortion coefficients using a set of chessboard images.
- Applied the distortion correction to raw images.
- Used color transforms, gradients, etc., to create a thresholded binary image and applied a perspective transform to rectify the image
- Detected lane pixels and fitted them to find the lane boundary.

### **Behavioral Cloning**

FEB 2017

- Used the image data and steering angles from the Udacity simulator to train a convolutional neural network and used this model to drive a car autonomously around the track.
- Used Keras to train, validate and test the model.

### **Traffic Sign Classifier**

JAN 2017

- Classified traffic signs using deep neural networks and convolutional neural networks.
- Used tensor flow for implementation

### **Finding Lane Lines on the Road**

DEC 2016

- Identified lane lines on the road in an image and a video stream
- Code written in Python and OpenCV

### **Text Summarizer**

OCT-NOV 2015

- Built a text summarizer to summarize emails
- Used snowball stemmer, tokenizer and wordnet to filter
- Used Naive Bayes for scoring
- Code written in Python

### **Build and train a robotic arm to help feed physically disabled**

JAN-MAY 2015

- Built a robotic arm with 6 DOF to identify, pickup and feed a food particle
- Used edge detection and blob detection to identify the food particle
- Used SVM, eigenfaces and Viola-Jones for detecting face and mouth and KLT algorithm for tracking
- Trained a neural networks using reinforcement learning to feed the food particle
- Code written in Python and OpenCV

### **Embedded Instrumentation system for Soil Nutrient Analysis**

JAN-MAY 2015

- Used spectroscopic methods to determine the relationships between color intensity and concentration of nutrients in soil samples
- Designed and built a portable embedded instrumentation system to detect color intensity
- Programmed Arduino Nano to calculate concentration
- Designed and built android app to display results over Bluetooth

### **Dipole Antenna Analysis using Numerical methods**

JAN-MAY 2014

- Analyzed current distribution for a thin wire antenna using delta gap excitation.
- Used Method of Moments to solve the Pocklington's Integral Equation to calculate current distribution.
- Calculated antenna parameters like Input impedance and Reflection coefficient using current distribution.
- Code written in MATLAB.

## **Sign Language Identifier for the Visually Impaired**

FEB-MAR 2013

- Used Machine Learning to classify Sign Language alphabets
- Used Gesture Dataset (2012) provided by Massey University for training and testing
- Used Principal Component Analysis for feature extraction and k-Nearest Neighbors for classification

## **PyAnagrammatic**

OCT-DEC 2011

- Two player game played over LAN
- Built in Python using Tkinter and Socket

## AWARDS AND ACCOLADES

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- Awarded the *Rising Star* award at Seven Lakes Technologies (December 2017)
- Recipient of *RBI Golden Jubilee Year Scholarship Scheme for Wards of Employees* for all semesters for excellent academic record
- Second Prize in Word-A-Maze conducted by Hindi Activities Society, BITS Pilani during APOGEE 2014.
- Among top 300 students shortlisted for Kishore Vaigyanik Protsahan Yojana (KVPY) scholarship program by Government of India
- AIR 75 in Mathematics Olympiad organized by Talent Search Institute in 2008.
- 3rd school rank and 10th state rank in National Science Olympiad 2008 organized by Science Olympiad Foundation.

## EXTRA-CURRICULAR

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- Performed at SHIAMAK Summer Funk 2017 and SHIAMAK Winter Funk 2016 - Dance festivals organized by the Shiamak Davar Institute of Performing Arts 2016-17
- Conducted workshop on Symbolic computation using Maple, October 2013
- Administered intra-college file-sharing platform for 2 years 2012-2014
- Participated in BITSMUN12 conference held from 18th to 20th February, 2012 February, 2012
- Participated in WordzMUN'08 conference held from 6th to 8th October, 2008 October, 2008

## COMMUNITY WORK

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- Responsible for distribution of provisions to families of kids disabled due to Cyanide poisoning from Kolar Gold Fields February 2016
- Cleaned and painted a Government school in rural Bangalore with help of Magic Bus Foundation January 2016
- Spent time with special children at Apoorva Center for Autism August 2015

## OTHER INFORMATION

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- Programming Languages:  
Experienced - C#, Python, Java, JavaScript, Objective C, HTML, CSS, PHP, MySQL  
Novice - Swift, C, C++, R, Verilog HDL, x86 Assembly Language.
- Software: MATLAB, Maple, LTSpice, Cadence, IBM SPSS Modeler, AutoCAD
- Open Source SW/HW: OpenCV, Arduino
- Human Languages: English, Hindi, Punjabi.
- Github: @HarshSharma12 (<https://github.com/HarshSharma12>)